

Designing Critical Digital Systems.

Formal Verification of a Token Player for Synchronously Executed Petri Nets.

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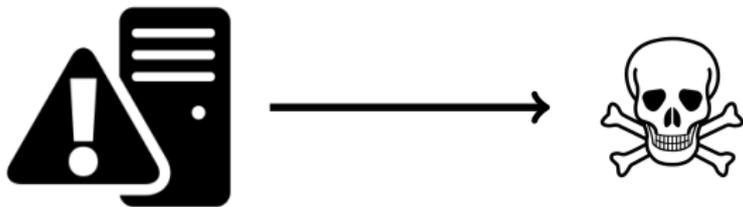
²NEURINNOV, Montpellier, France
David.Andreu@neurinnov.com

SHARC, July 2019

Context.

CRITICAL DIGITAL SYSTEMS (CDS)?

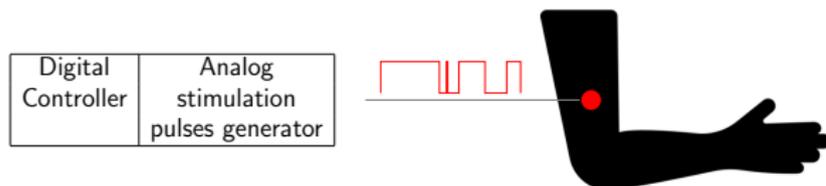
CRITICAL DIGITAL SYSTEMS (CDS)



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- ▶ Avionics: engine control, air traffic control. . .
- ▶ Medicine: surgical robots, radiotherapy systems. . .
- ▶ Spaceflight: launcher systems, crew transfer systems. . .
- ▶ Nuclear: reactor control systems. . .
- ▶ Infrastructure: fire alarm, telecommunications. . .
- ▶ And many more. . .

Medical Implants: A Concrete Example of CDS.



- ▶ Electrode receives electric current from stimulation generator.
- ▶ Digital controller gives instruction to stimulation generator.

Need for Safety and Certification.

CE Certification for Medical Devices. ¹

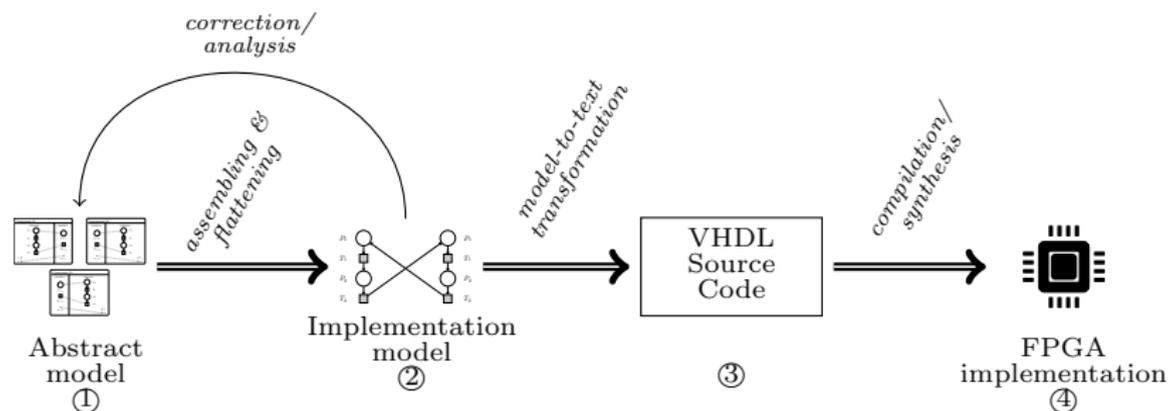
- ▶ European Regulation on Medical Devices (2017/745).
- ▶ Requires numerous tests on devices (technologic, clinical).

The Perks of Formal Methods.

- ▶ Many approaches: model checking, abstract interpretation, deductive methods. . .
- ▶ Deductive methods: test exhaustiveness through proofs.

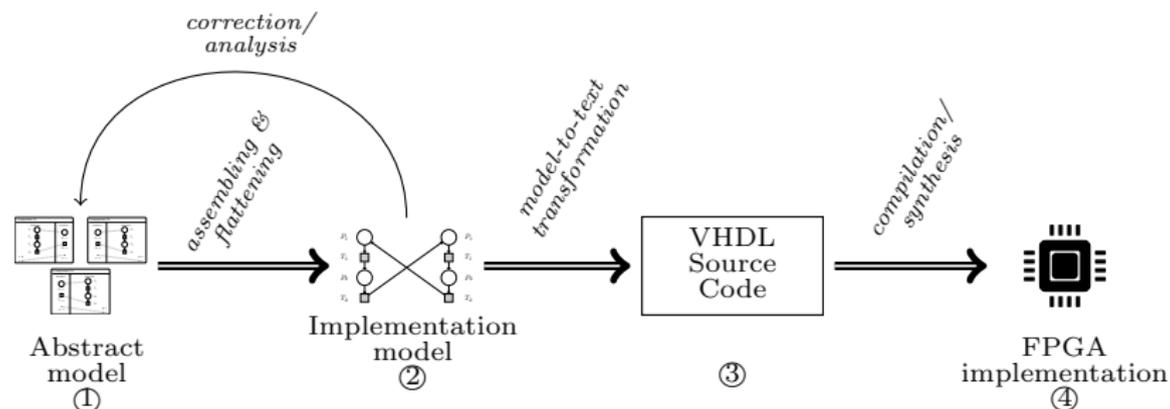
¹<https://eur-lex.europa.eu/legal-content/EN/TXT/?uri=CELEX:32017R0745>

HILECOP: A Process to Design and Implement CDS.



- ▶ Developed at INRIA (CAMIN Team).

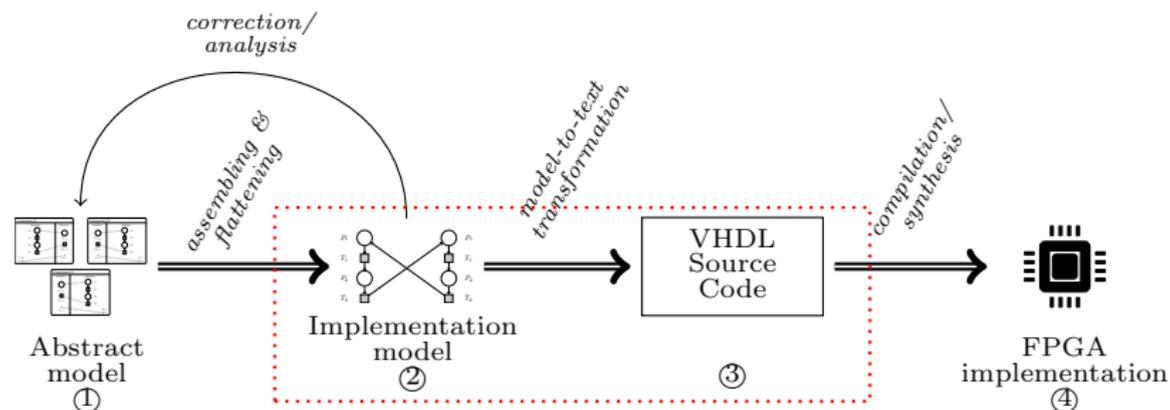
Formal Methods for HILECOP.



Verification of HILECOP.

- ▶ Ensure model correctness (analysis).
- ▶ Ensure behavior preservation through transformation.

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Deductive Methods for HILECOP.

Deductive Methods with the Coq Proof Assistant.

- ▶ General-purpose Programming Language.
- ▶ Proof Language.

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Proof steps.

Inspired by *CompCert*, a formally verified C compiler:

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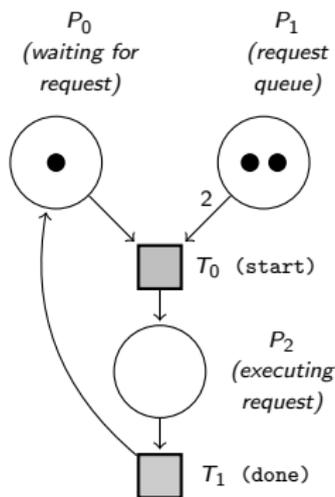
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1. Model the semantics of the *source language* (i.e, Petri nets).
2. Model the semantics of the *target language* (i.e, VHDL).
3. Implement the transformation.
4. Prove behavior preservation.

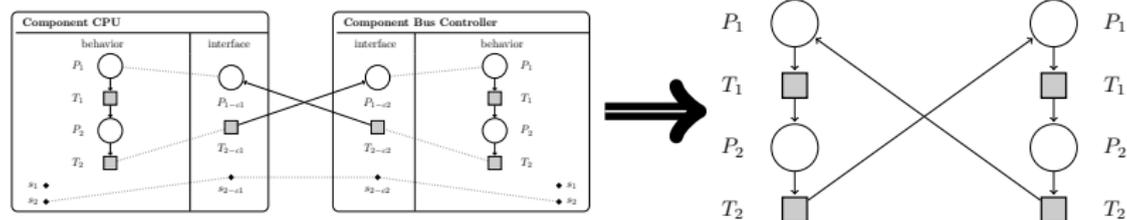
Presentation of HILECOP Petri Nets.

The Petri Net (PN) Formalism.

- ▶ To model *dynamic systems*.
- ▶ Directed weighted graph.
- ▶ Places (\approx states or resources) and transitions (\approx events).
- ▶ Marking: current state of the system.
- ▶ Sensitization: a transition t is ready to be fired.



HILECOP High-Level Models.

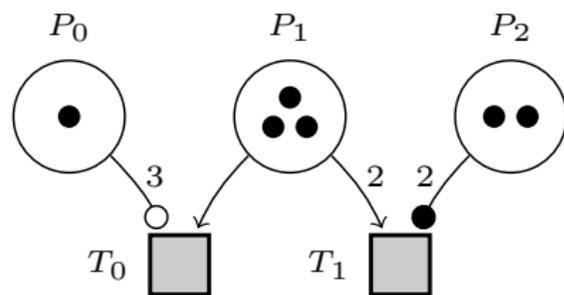


- ▶ Assembling components.
- ▶ Flattening model.

HILECOP PNs (SITPNs).

HILECOP Petri Nets are:

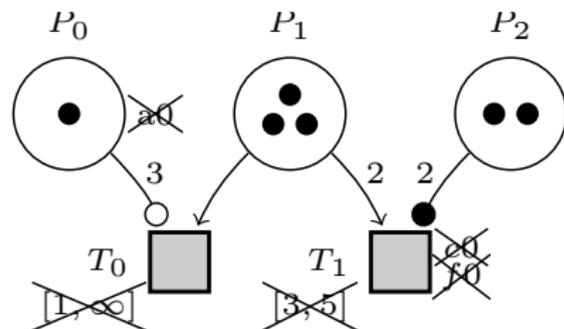
- ▶ **S**ynchronously executed (with priorities)
- ▶ **G**eneralized
- ▶ **E**xtended
- ▶ **I**nterpreted
- ▶ **T**ime
- ▶ with macroplaces
- ▶ **P**etri **N**ets



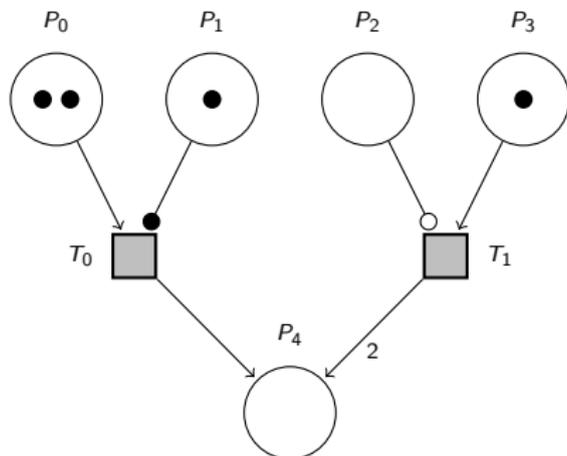
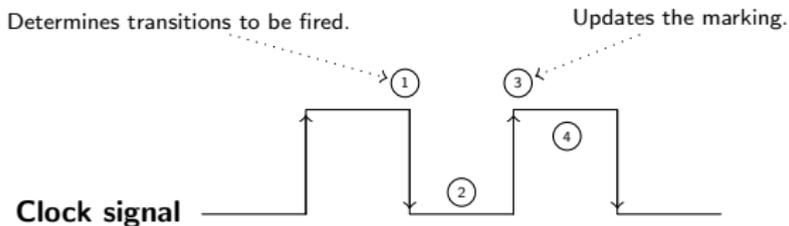
HILECOP PN_s (SITPN_s).

HILECOP Petri Nets are:

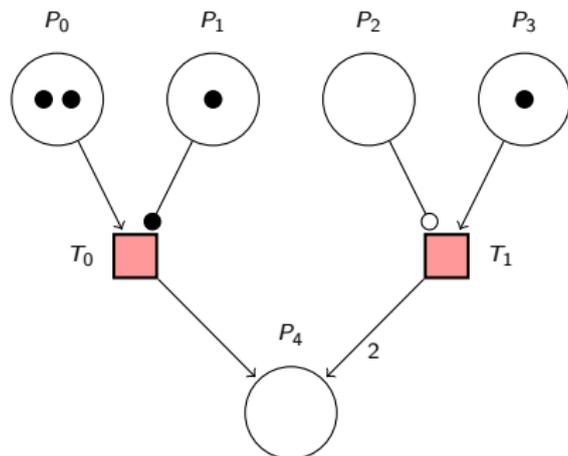
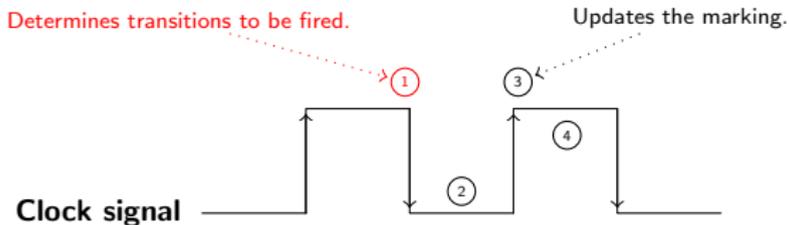
- ▶ Synchronously executed (with priorities)
- ▶ generalized
- ▶ extended
- ▶ Interpreted
- ▶ Time
- ▶ with macroplaces
- ▶ Petri Nets



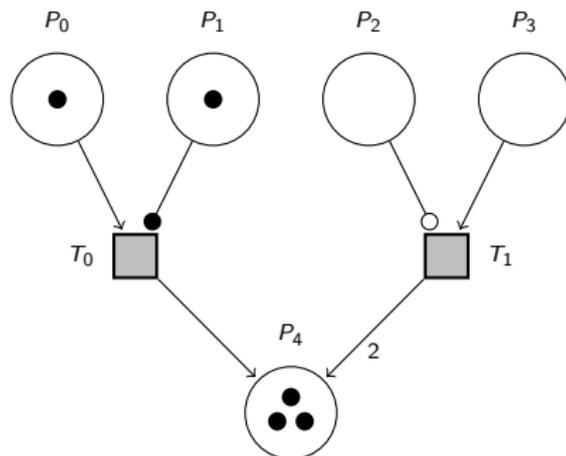
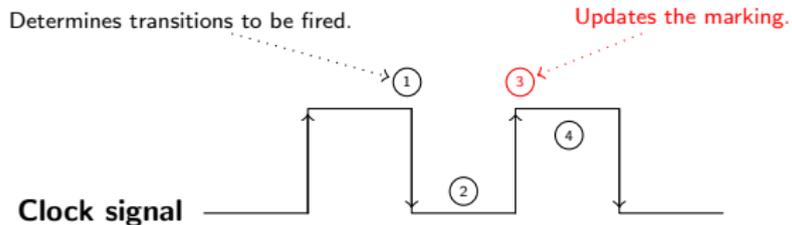
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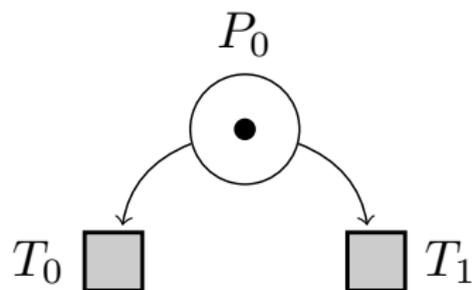
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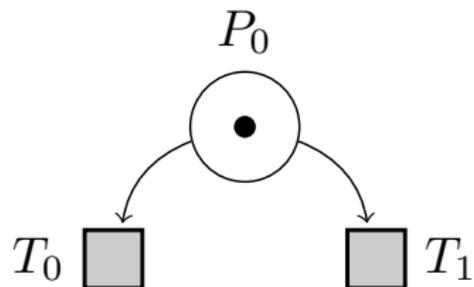
Conflicts and priorities.



Conflict types.

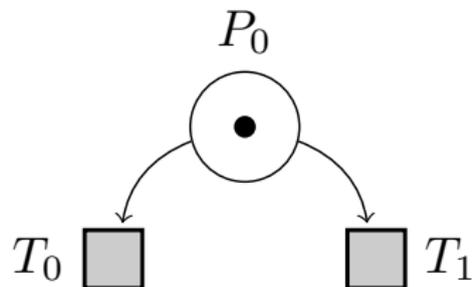
- ▶ Structural: T_0 and T_1 have P_0 as a common input place.
- ▶ Effective: the firing of T_0 disables T_1 , and conversely.

Conflicts and priorities.



Which transition will be fired?

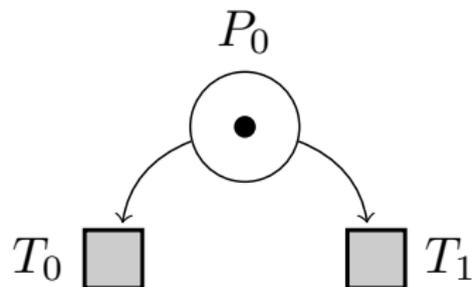
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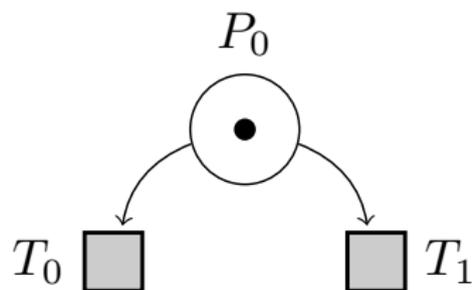
Conflicts and priorities.



Which transition will be fired?

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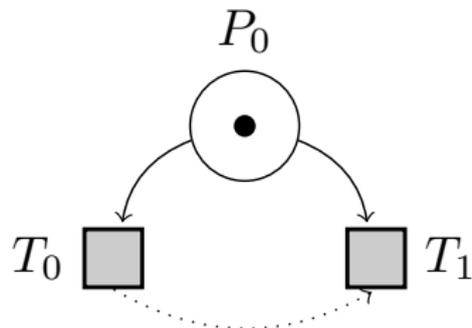
Conflicts and priorities.



Which transition will be fired?

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- ▶ If synchronous execution: T_0 and T_1 

Conflicts and priorities.



Priority relation.

T_0 has a higher firing priority than T_1 .

Formalizing HILECOP Petri Nets.

Formal Definition of SPNs.

A synchronously executed, extended, and generalized Petri net with priorities is a tuple

$\langle P, T, pre, test, inhib, post, M_0, clock, \succ \rangle$

where we have:

1. $P = \{P_0, \dots, P_n\}$ a set of places.
2. $T = \{T_0, \dots, T_n\}$ a set of transitions.
3. $pre \in P \rightarrow T \rightarrow \mathbb{N}$.
4. $test \in P \rightarrow T \rightarrow \mathbb{N}$.
5. $inhib \in P \rightarrow T \rightarrow \mathbb{N}$.
6. $post \in T \rightarrow P \rightarrow \mathbb{N}$.
7. $M_0 \in P \rightarrow \mathbb{N}$, the initial marking of the SPN.
8. \succ , the priority relation, which represents the firing priority between transitions of the same priority group.

Implementation of SPNs in Coq.

```
1 Structure Spn : Set :=
2   mk_Spn {
3     places : list Place;
4     transs : list Trans;
5     pre : Place → Trans → nat;
6     test : Place → Trans → nat;
7     inhib : Place → Trans → nat;
8     post : Trans → Place → nat;
9     initial_marking : Place → nat;
10    priority_groups : list (list Trans);
11    lneighbors : Trans → Neighbors;
12  }.
```

- ▶ Record with multiple fields.
- ▶ lneighbors field associates transitions to input/output places.

Definitions and Notations.

Remark.

The following definitions are given under the scope of a SPN $\langle P, T, pre, test, inhib, post, M_0, \succ \rangle$.

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Definition (SPN state)

A SPN state is a couple $(Fired, M)$ where $M \in P \rightarrow \mathbb{N}$ is the current marking of SPN and $Fired \subseteq T$ is a list of transitions.

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A SPN state is a couple $(Fired, M)$ where $M \in P \rightarrow \mathbb{N}$ is the current marking of SPN and $Fired \subseteq T$ is a list of transitions.

Definition (Sensitization and Firability)

- ▶ Sensitization: A transition $t \in sens(M)$, if $M \geq pre(t)$, and $M \geq test(t)$, and $M < inhib(t)$ or $inhib(t) = 0$.
- ▶ Firability: A transition $t \in firable(s)$, where $s = (Fired, M)$, if $t \in sens(M)$.

SPN Semantics.

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The semantics of an SPN is represented by the triplet $\langle S, s_0, \rightsquigarrow \rangle$
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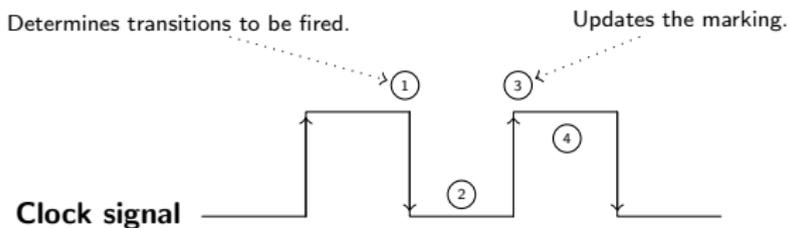
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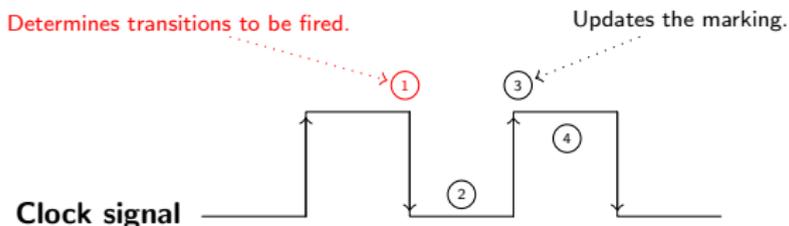
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- ▶ S is the set of states of the SPN.
- ▶ $s_0 = (\emptyset, M_0)$ is the initial state of the SPN.
- ▶ $\rightsquigarrow \subseteq S \times Clk \times S$ is the state changing relation, which is noted $s \xrightarrow{clk} s'$ where $s, s' \in S$, $Clk = \{\downarrow clock, \uparrow clock\}$ and $clk \in Clk$.

SPN State Changing Relation (Falling Edge).

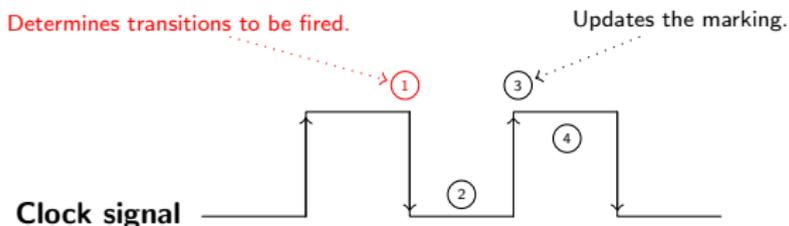


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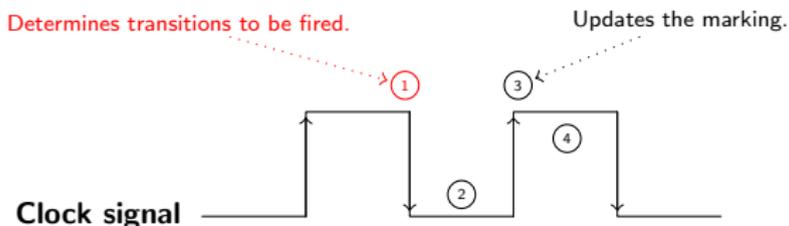
► $s = (Fired, M) \xrightarrow{\text{clock}} s' = (Fired', M)$ if:

SPN State Changing Relation (Falling Edge).



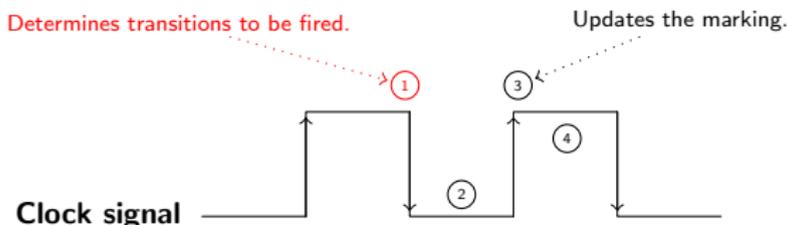
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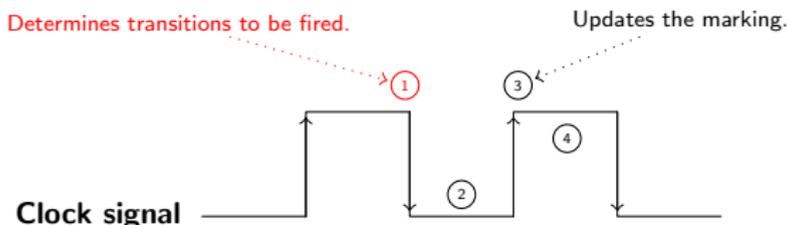
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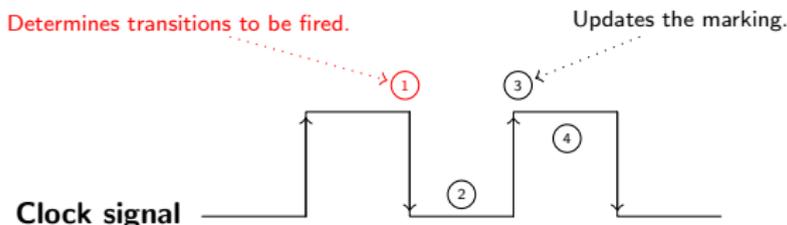
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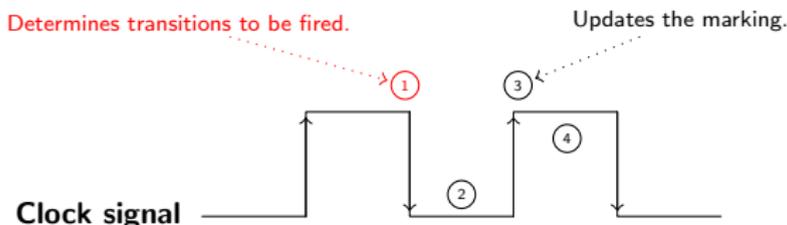
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where $Pr(t) = \{t_i \mid t_i \succ t \wedge t_i \in Fired'\}$.

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An Example of SPN Semantics Rule.

All transitions both firable and sensitized by the residual marking are fired.

$$s = (Fired, M) \xrightarrow[\sim]{clock} s' = (Fired', M)$$

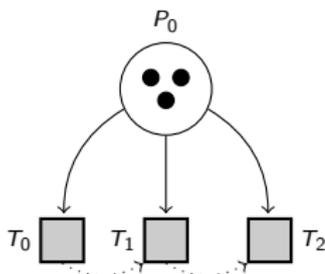


Figure: At state s .

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► $T_0, T_1 \in \text{Fired}'$

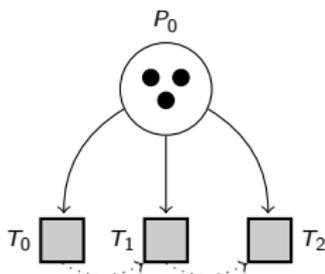


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▶ $T_2 \in \text{Fired}'?$

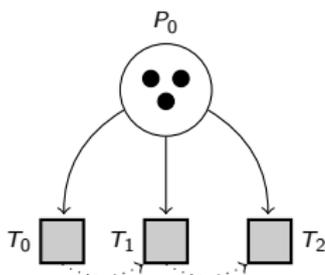


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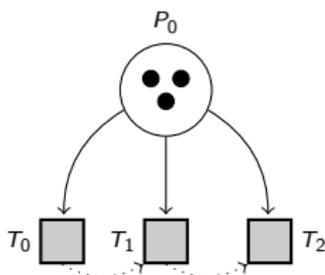


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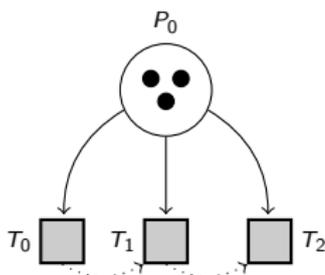


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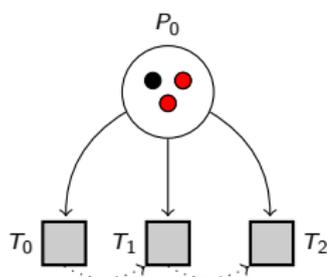


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YES!
- ▶ $M_R = (P_0, 1), T_2 \in sens(M_R)?$

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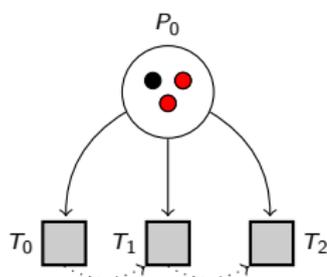


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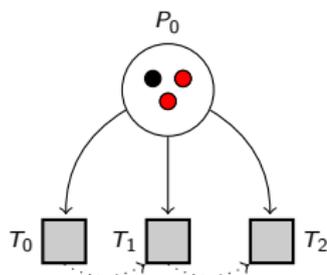
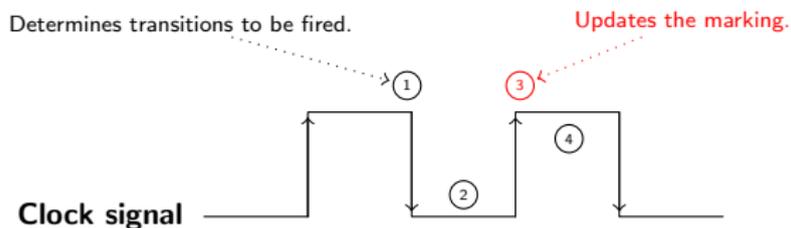


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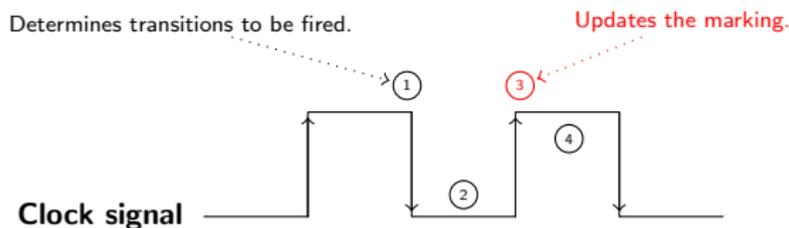
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YES!
- ▶ $M_R = (P_0, 1), T_2 \in \text{sens}(M_R)?$
YES!
- ▶ Then, according to rule 2 of SPN semantics: $T_2 \in Fired'$

SPN State Changing Relation (Rising Edge).



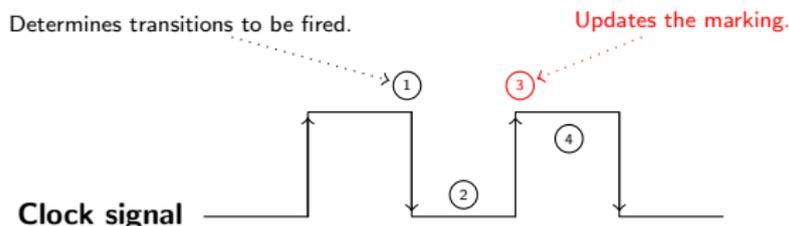
► $s = (Fired, M) \xrightarrow{\uparrow \text{clock}} \rightsquigarrow s' = (Fired, M')$:

SPN State Changing Relation (Rising Edge).



- ▶ $s = (Fired, M) \xrightarrow{\uparrow clock} \rightsquigarrow s' = (Fired, M')$:
 - ▶ M' is the new marking resulting from the firing of all transitions contained in Fired, i.e.:

SPN State Changing Relation (Rising Edge).



- ▶ $s = (Fired, M) \xrightarrow{\uparrow clock} s' = (Fired, M')$:
 - ▶ M' is the new marking resulting from the firing of all transitions contained in Fired, i.e.:
$$M' = M - \sum_{t_i \in Fired} (pre(t_i) - post(t_i)).$$

SPN Semantics in Coq.

```
1 Inductive SpnSemantics (spn : Spn) (s s' : SpnState) : Clock → Prop :=
2 | SpnSemantics_falling_edge :
3   (* Rules 1, 2 and 3 *)
4   ... → SpnSemantics spn s s' falling_edge
5 | SpnSemantics_rising_edge :
6   (* Ensures the consistency of spn, s and s'. *)
7   IsWellDefinedSpn spn →
8   IsWellDefinedSpnState spn s →
9   IsWellDefinedSpnState spn s' →
10  (* Fired stays the same between state s and s'. *)
11  s.(fired) = s'.(fired) →
12  (* Rule 4 of SPN semantics. *)
13  (forall (p : Place) (n : nat),
14   (p, n) ∈ s.(marking) →
15   (p, n - (presum spn p s.(fired)) + (postsum spn p s'.(fired))) ∈ s'.(marking)) →
16  SpnSemantics spn s s' rising_edge.
```

- ▶ $s.(marking)$ expresses the marking at state s .
- ▶ Markings are list of couples (*place, number of tokens*).

SPN Token Player Program.

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- ▶ Implementation of the SPN semantics rules.

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- ▶ Computes the evolution of a given SPN from initial state s_0 to state s_n , where n is the number of evolution cycles.

SPN Token Player Program.

- ▶ Implementation of the SPN semantics rules.
- ▶ Computes the evolution of a given SPN from initial state s_0 to state s_n , where n is the number of evolution cycles.
- ▶ Gives us confidence in our implementation of SPN semantics.

An Algorithm for one cycle of evolution.

Data: *spn*, an SPN. *s*, the state of *spn* at the beginning of the clock cycle.

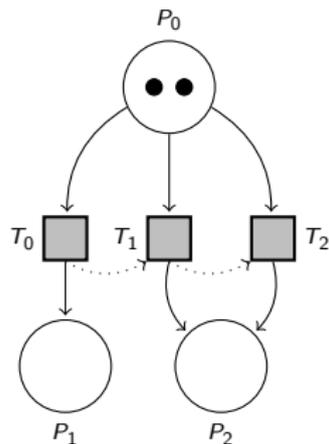
Result: A couple of SPN states, *s'* and *s''*, results of the evolution of *spn* from state *s*.

```
1 begin
2   fired_transitions ← []
3   /* Phase 1, falling edge of the clock. */
4   foreach priority_group in spn.priority_groups do
5     resid_m ← s.marking
6     foreach trans in priority_group do
7       if is_firable(trans, s) and is_sensitized(trans, resid_m) then
8         update_residual_marking(trans, resid_m)
9         push_back(trans, fired_transitions)
10
11  s' ← make_state(fired_transitions, s.marking)
12
13  /* Phase 2, rising edge of the clock. */
14  new_marking ← s'.marking
15  foreach trans in fired_transitions do
16    update_marking_pre(trans, new_marking)
17    update_marking_post(trans, new_marking)
18
19  s'' ← make_state(s'.fired, new_marking)
20  return (s', s'')
```

Algorithm 1: cycle(*spn*, *s*)

Execution on An Example.

Falling edge phase.

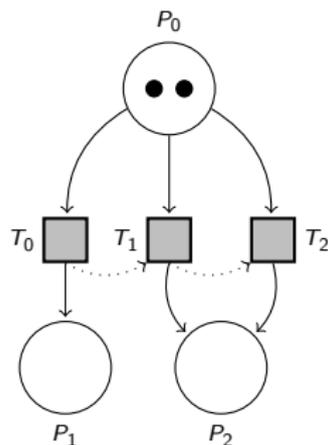


```
fired_transitions ← []  
foreach priority_group in spn.priority_groups do  
  resid_m ← s.marking  
  foreach trans in priority_group do  
    if is_firable(trans, s) and is_sensitized(trans, resid_m)  
    then  
      update_residual_marking(trans, resid_m)  
      push_back(trans, fired_transitions)  
  
s' ← make_state(fired_transitions, s.marking)
```

$s = (\text{fired}, \text{marking})$ with $s.\text{marking} = (P_0, 2), (P_1, 0), (P_2, 0)$
 $\text{priority_groups} = [[T_0, T_1, T_2]]$

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
```

```
  resid_m ← s.marking
```

```
  foreach trans in priority_group do
```

```
    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

```
        update_residual_marking(trans, resid_m)
```

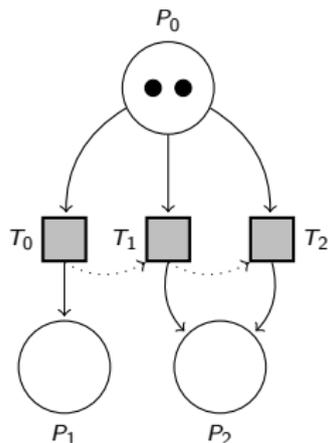
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

```
priority_groups = [ [T0, T1, T2] ]  
fired_transitions = []
```

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
```

```
  resid_m ← s.marking
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```
  foreach trans in priority_group do
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    if is_firable(trans, s) and is_sensitized(trans, resid_m)
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      then
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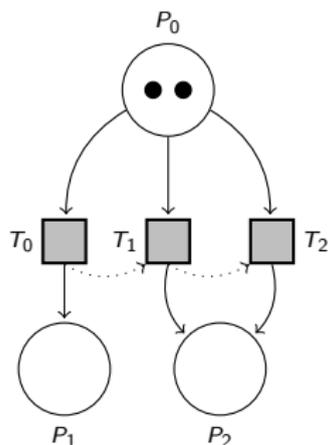
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

```
priority_groups = [ [  $T_0$ ,  $T_1$ ,  $T_2$  ] ]  
fired_transitions = []  
priority_group = [  $T_0$ ,  $T_1$ ,  $T_2$  ]
```

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
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```
  resid_m ← s.marking
```

```
  foreach trans in priority_group do
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    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

```
        update_residual_marking(trans, resid_m)
```

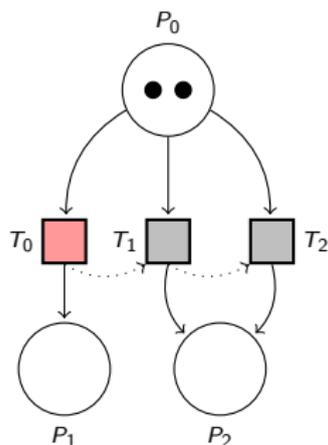
```
        push_back(trans, fired_transitions)
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```
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = []  
priority_group = [T0, T1, T2]  
resid_m = (P0, 2), (P1, 0), (P2, 0)
```

Execution on An Example.

Falling edge phase.



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fired_transitions ← []
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```
foreach priority_group in spn.priority_groups do
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  resid_m ← s.marking
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```
  foreach trans in priority_group do
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```
    if is_firable(trans, s) and is_sensitized(trans, resid_m)
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```
      then
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        update_residual_marking(trans, resid_m)
```

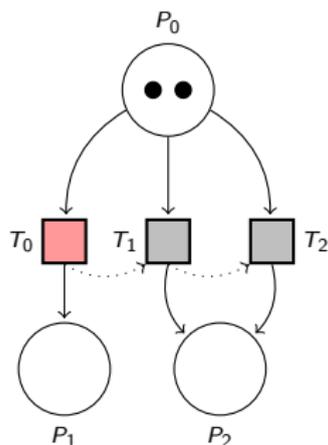
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fired_transitions = []  
priority_group = [T0, T1, T2]  
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Execution on An Example.

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foreach priority_group in spn.priority_groups do
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    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

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        update_residual_marking(trans, resid_m)
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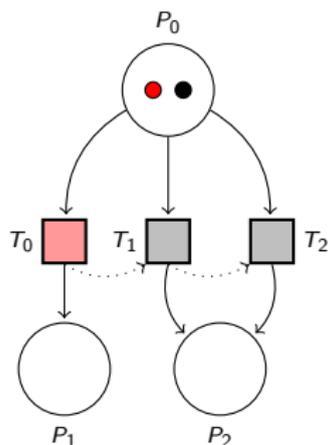
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```
s' ← make_state(fired_transitions, s.marking)
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```
fired_transitions = []  
priority_group = [T0, T1, T2]  
resid_m = (P0, 2), (P1, 0), (P2, 0)
```

Execution on An Example.

Falling edge phase.

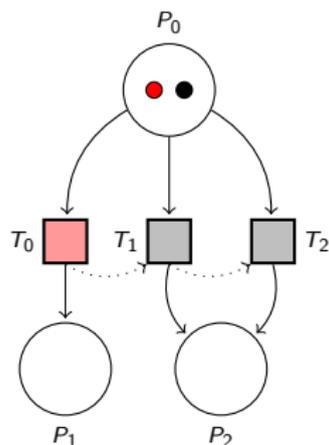


```
fired_transitions ← []  
  
foreach priority_group in spn.priority_groups do  
  resid_m ← s.marking  
  
  foreach trans in priority_group do  
    if is_firable(trans, s) and is_sensitized(trans, resid_m)  
      then  
        update_residual_marking(trans, resid_m)  
        push_back(trans, fired_transitions)  
  
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = []  
priority_group = [ $T_0$ ,  $T_1$ ,  $T_2$ ]  
resid_m = ( $P_0$ , 1), ( $P_1$ , 0), ( $P_2$ , 0)
```

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
```

```
  resid_m ← s.marking
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  foreach trans in priority_group do
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    if is_firable(trans, s) and is_sensitized(trans, resid_m)
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      then
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        update_residual_marking(trans, resid_m)
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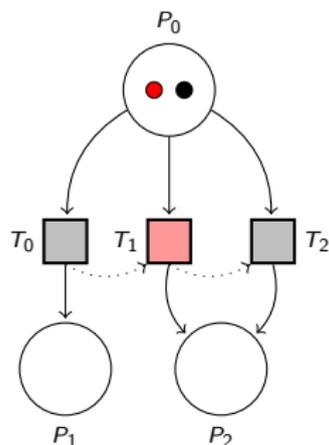
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = [T0]  
priority_group = [T0, T1, T2]  
resid_m = (P0, 1), (P1, 0), (P2, 0)
```

Execution on An Example.

Falling edge phase.



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fired_transitions ← []
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foreach priority_group in spn.priority_groups do
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  resid_m ← s.marking
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  foreach trans in priority_group do
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```
    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

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        update_residual_marking(trans, resid_m)
```

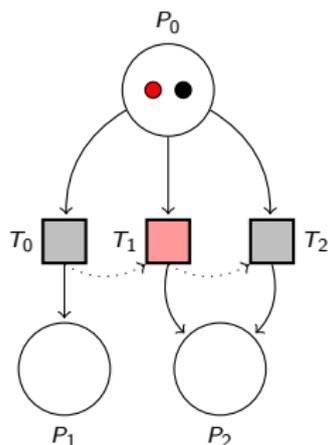
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = [T0]  
priority_group = [T0, T1, T2]  
resid_m = (P0, 1), (P1, 0), (P2, 0)
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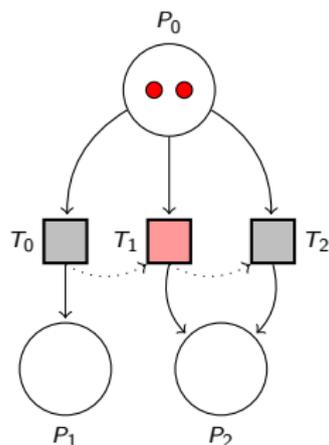
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fired_transitions = [T0]  
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Execution on An Example.

Falling edge phase.

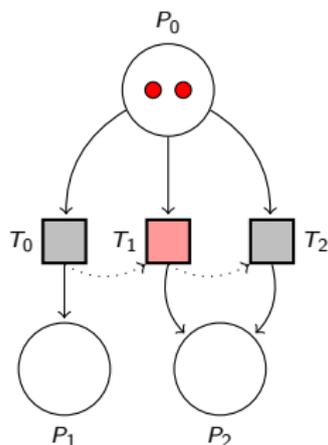


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  resid_m ← s.marking  
  foreach trans in priority_group do  
    if is_firable(trans, s) and is_sensitized(trans, resid_m)  
    then  
      update_residual_marking(trans, resid_m)  
      push_back(trans, fired_transitions)  
  
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = [ $T_0$ ]  
priority_group = [ $T_0$ ,  $T_1$ ,  $T_2$ ]  
resid_m = ( $P_0$ , 0), ( $P_1$ , 0), ( $P_2$ , 0)
```

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
```

```
  resid_m ← s.marking
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```
  foreach trans in priority_group do
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```
    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

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        update_residual_marking(trans, resid_m)
```

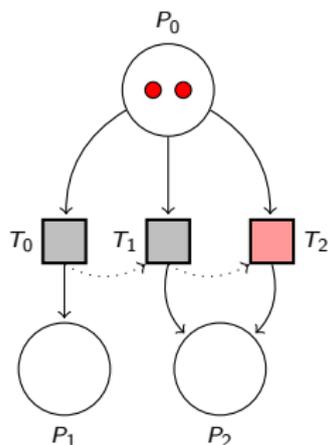
```
        push_back(trans, fired_transitions)
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```
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = [ $T_0$ ,  $T_1$ ]  
priority_group = [ $T_0$ ,  $T_1$ ,  $T_2$ ]  
resid_m = ( $P_0$ , 0), ( $P_1$ , 0), ( $P_2$ , 0)
```

Execution on An Example.

Falling edge phase.



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      then
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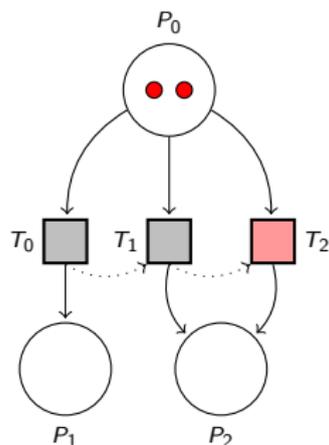
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```

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fired_transitions = [ $T_0$ ,  $T_1$ ]  
priority_group = [ $T_0$ ,  $T_1$ ,  $T_2$ ]  
resid_m = ( $P_0$ , 0), ( $P_1$ , 0), ( $P_2$ , 0)
```

Execution on An Example.

Falling edge phase.



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```

```
foreach priority_group in spn.priority_groups do
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  resid_m ← s.marking
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```
  foreach trans in priority_group do
```

```
    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

```
        update_residual_marking(trans, resid_m)
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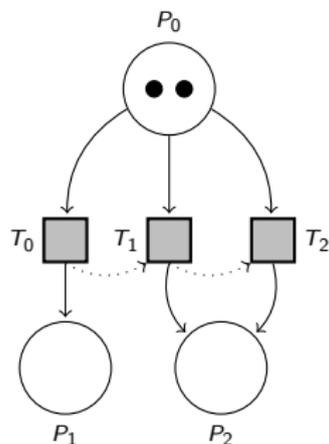
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

```
fired_transitions = [ $T_0$ ,  $T_1$ ]  
priority_group = [ $T_0$ ,  $T_1$ ,  $T_2$ ]  
resid_m = ( $P_0$ , 0), ( $P_1$ , 0), ( $P_2$ , 0)
```

Execution on An Example.

Falling edge phase.



```
fired_transitions ← []
```

```
foreach priority_group in spn.priority_groups do
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  resid_m ← s.marking
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  foreach trans in priority_group do
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    if is_firable(trans, s) and is_sensitized(trans, resid_m)
```

```
      then
```

```
        update_residual_marking(trans, resid_m)
```

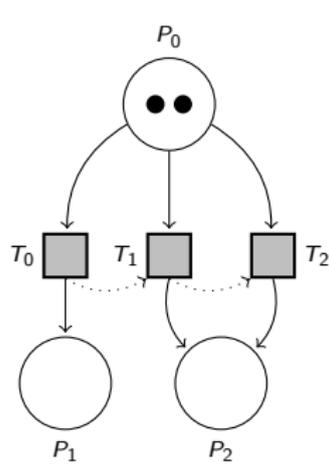
```
        push_back(trans, fired_transitions)
```

```
s' ← make_state(fired_transitions, s.marking)
```

$$s' = ([T_0, T_1], [(P_0, 2), (P_1, 0), (P_2, 0)])$$

Execution on An Example.

Rising edge phase.



```
new.marking ← s'.marking
```

```
foreach trans in fired_transitions do
```

```
  update_marking_pre(trans, new_marking)
```

```
  update_marking_post(trans, new_marking)
```

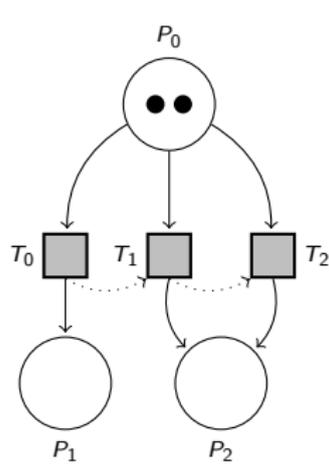
```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

$$s' = ([T_0, T_1], [(P_0, 2), (P_1, 0), (P_2, 0)])$$
$$\text{fired_transitions} = [T_0, T_1]$$

Execution on An Example.

Rising edge phase.



```
new_marking ← s'.marking
```

```
foreach trans in fired_transitions do
```

```
  update_marking_pre(trans, new_marking)
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  update_marking_post(trans, new_marking)
```

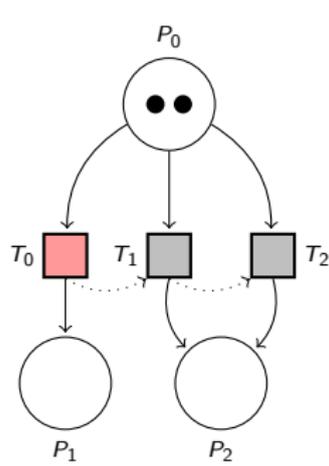
```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

```
fired_transitions = [ $T_0$ ,  $T_1$ ]  
new_marking = ( $P_0, 2$ ), ( $P_1, 0$ ), ( $P_2, 0$ )
```

Execution on An Example.

Rising edge phase.



```
new.marking ← s'.marking
```

```
foreach trans in fired_transitions do
```

```
  update_marking_pre(trans, new_marking)
```

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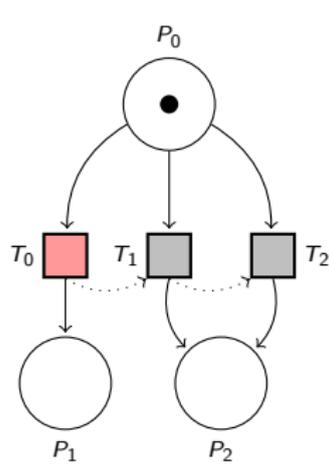
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s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
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```
fired_transitions = [ $T_0$ ,  $T_1$ ]  
new_marking = ( $P_0, 2$ ), ( $P_1, 0$ ), ( $P_2, 0$ )
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Execution on An Example.

Rising edge phase.



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new.marking ← s'.marking
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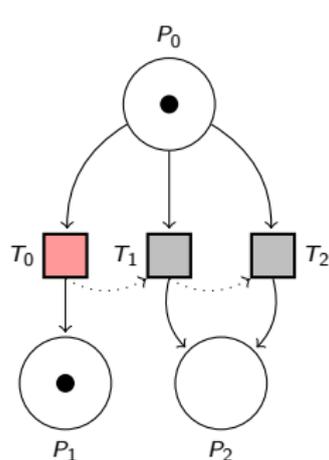
```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

```
fired_transitions = [T0, T1]  
new_marking = (P0, 1), (P1, 0), (P2, 0)
```

Execution on An Example.

Rising edge phase.



```
new.marking ← s'.marking
```

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foreach trans in fired_transitions do
```

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  update_marking_pre(trans, new_marking)
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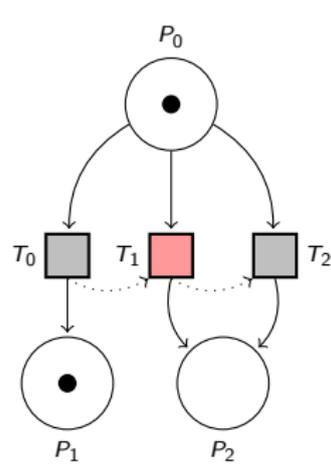
```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

fired_transitions = [T_0, T_1]
new_marking = ($P_0, 1$), ($P_1, 1$), ($P_2, 0$)

Execution on An Example.

Rising edge phase.



```
new.marking ← s'.marking
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```
foreach trans in fired_transitions do
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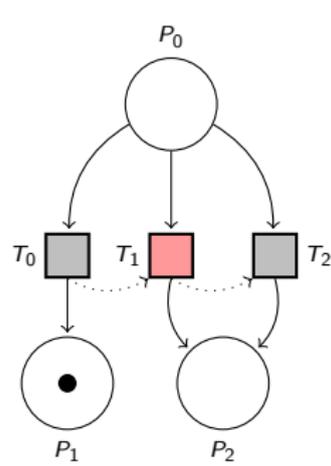
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s'' ← make_state(s'.fired, new_marking)
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return (s', s'')
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```
fired_transitions = [ $T_0, T_1$ ]  
new_marking = ( $P_0, 1$ ), ( $P_1, 1$ ), ( $P_2, 0$ )
```

Execution on An Example.

Rising edge phase.



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new.marking ← s'.marking
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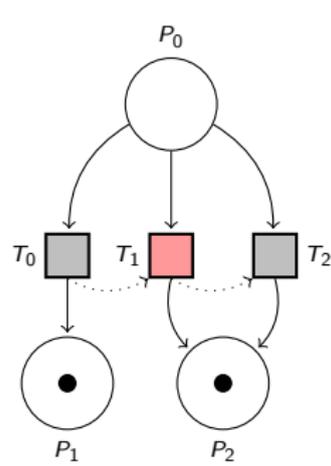
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s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

```
fired_transitions = [T0, T1]  
new_marking = (P0, 0), (P1, 1), (P2, 0)
```

Execution on An Example.

Rising edge phase.



```
new_marking ← s'.marking
```

```
foreach trans in fired_transitions do
```

```
  update_marking_pre(trans, new_marking)
```

```
  update_marking_post(trans, new_marking)
```

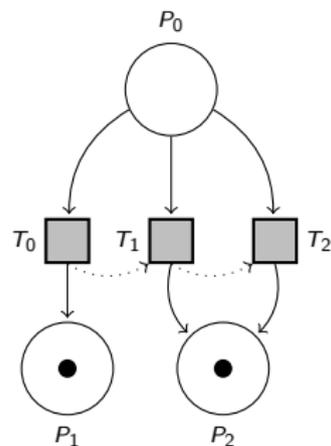
```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

```
fired_transitions = [T0, T1]  
new_marking = (P0, 0), (P1, 1), (P2, 1)
```

Execution on An Example.

Rising edge phase.



```
new_marking  $\leftarrow$  s'.marking
```

```
foreach trans in fired_transitions do
```

```
    update_marking_pre(trans, new_marking)
```

```
    update_marking_post(trans, new_marking)
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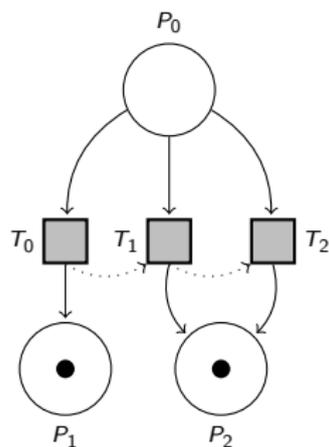
```
s''  $\leftarrow$  make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

$$s'' = ([T_0, T_1], [(P_0, 0), (P_1, 1), (P_2, 1)])$$

Execution on An Example.

Rising edge phase.



```
new_marking ← s'.marking
```

```
foreach trans in fired_transitions do
```

```
    update_marking_pre(trans, new_marking)
```

```
    update_marking_post(trans, new_marking)
```

```
s'' ← make_state(s'.fired, new_marking)
```

```
return (s', s'')
```

$$s' = ([T_0, T_1], [(P_0, 2), (P_1, 0), (P_2, 0)])$$

$$s'' = ([T_0, T_1], [(P_0, 0), (P_1, 1), (P_2, 1)])$$

Correctness/Completeness of The SPN Token Player.

Theorem (Correctness)

$\forall (spn : Spn) (s s' s'' : SpnState)$, which are well-defined,
 $cycle\ spn\ s = (s', s'') \Rightarrow s \xrightarrow[\rightsquigarrow]{\downarrow\ clock} s' \xrightarrow[\rightsquigarrow]{\uparrow\ clock} s''$.

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- ▶ Formal verification of a model-to-text transformation from HILECOP PNs to VHDL.
- ▶ First step: model the semantics of HILECOP PNs (SITPNs).

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Done.

Model the semantics of SPNs (subclass of HILECOP PNs).

Conclusion.

Context.

- ▶ Formal verification of a model-to-text transformation from HILECOP PNs to VHDL.
- ▶ First step: model the semantics of HILECOP PNs (SITPNs).

Done.

Model the semantics of SPNs (subclass of HILECOP PNs).

On Going.

Add time, interpretation and macroplaces to SPNs semantics.

Thank you for your attention!

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Coq Implementation of the SPN Token Player.

```
1 Definition spn_cycle (spn : Spn) (starting_state : SpnState) :
2   option (SpnState * SpnState) :=
3   (* Computes the transitions to be fired. *)
4   match spn_falling_edge spn starting_state with
5   | Some inter_state =>
6     (* Updates the marking. *)
7     match spn_rising_edge spn inter_state with
8     | Some final_state => Some (inter_state, final_state)
9     | None => None
10    end
11  | None => None
12  end.
```

Figure: The SPN Token Player Program in Coq.

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Figure: The SPN Token Player Program in Coq.

- ▶ `match` checks the result of function calls.

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Figure: The SPN Token Player Program in Coq.

- ▶ `match` checks the result of function calls.
- ▶ Functions return `Some` value or `None` (error case).

Reminder on Correctness and Completeness.

- ▶ Let X, Y be two types.
- ▶ Let $P \in X \rightarrow Y$ be a program, that takes $x \in X$ as an input value and returns some $y \in Y$.
- ▶ Let $S \in X \rightarrow Y \rightarrow \{\top, \perp\}$ be the specification of program P . S is a predicate that takes x and y as input values and return True or False.

Definition (Correctness)

A program P is said to be correct regarding its specification if
 $\forall x \in X, y \in Y, P(x) = y \Rightarrow S(x, y)$

Definition (Completeness)

A program P is said to be complete regarding its specification if
 $\forall x \in X, y \in Y, S(x, y) \Rightarrow P(x) = y$

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Lemma (Falling Edge Correct)

$\forall (spn : Spn) (s s' : SpnState)$, which are well-defined,
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Falling Edge Correct Proof.

- ▶ Induction on the priority groups of spn .
- ▶ With the help of other lemmas:
 - ① $is_sensitized(t, M) \Leftrightarrow t \in sens(M)$
 - ② $is_firable(t, s) \Leftrightarrow t \in firable(s)$
 - ③ $spn_falling_edge$ computes a proper residual marking.
 - ④ ...



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Rising Edge Correct Proof.

- ▶ Induction on the list of transitions to be fired of state s .
- ▶ With the help of other lemmas:

- 1 $update_marking_pre(t, M) = Some\ M'$
 $\Leftrightarrow M' = M - \sum_{t_i \in Fired} pre(t_i)$
- 2 $update_marking_post(t, M) = Some\ M'$
 $\Leftrightarrow M' = M + \sum_{t_i \in Fired} post(t_i)$
- 3 ...



Completeness of The SPN Token Player.

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